# INSTRUCTION MANUAL

# PNP TRANSISTOR OUTPUT MODULE

(32 points, MECHATROLINK- I/II use)

MODEL R7K4FML-6-DC32B

# **BEFORE USE ....**

Thank you for choosing M-System. Before use, please check contents of the package you received as outlined below. If you have any problems or questions with the product, please contact M-System's Sales Office or representatives.

#### ■ PACKAGE INCLUDES:

Discrete output module	(1)
Mounter slider	(2)

#### ■ MODEL NO.

Confirm that the model number described on the product is exactly what you ordered.

#### **■ INSTRUCTION MANUAL**

This manual describes necessary points of caution when you use this product, including installation, connection and basic maintenance procedures.

# **POINTS OF CAUTION**

### **■ CONFORMITY WITH EU DIRECTIVES**

• The actual installation environments such as panel configurations, connected devices and connected wires may affect the protection level of this unit when it is integrated in a panel system. The user may have to review the CE requirements in regard to the whole system and employ additional protective measures to ensure CE conformity.

#### **■ POWER INPUT RATING & OPERATIONAL RANGE**

 Locate the power input rating marked on the product and confirm its operational range as indicated below: 24V DC rating: 24V ±10%, approx. 60mA

#### **■ GENERAL PRECAUTIONS**

- Before you remove the unit or mount it, turn off the power supply and input signal for safety.
- · Before you remove the terminal block or mount it, turn off the power supply and output signal for safety.

#### **■ ENVIRONMENT**

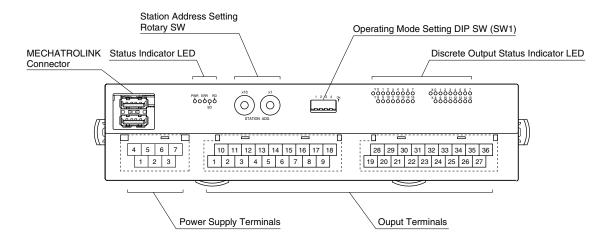
- Indoor use
- When heavy dust or metal particles are present in the air, install the unit inside proper housing with sufficient ven-
- Do not install the unit where it is subjected to continuous vibration. Do not subject the unit to physical impact.
- Environmental temperature must be within 0 to 55°C (32 to 131°F) with relative humidity within 30 to 90% RH in order to ensure adequate life span and operation.

### **■ WIRING**

- Do not install cables close to noise sources (relay drive cable, high frequency line, etc.).
- Do not bind these cables together with those in which noises are present. Do not install them in the same duct.

• The unit is designed to function as soon as power is supplied, however, a warm up for 10 minutes is required for satisfying complete performance described in the data sheet.

# **FRONT VIEW**



#### **■ STATUS INDICATOR LED**

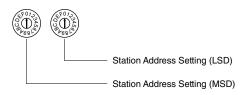
ID	COLOR	FUNCTION
PWR	Green	Turns on when the internal power is supplied normally.
ERR	Red	Turns on in no station address setting error.
SD	Green	Turns on when the module is transmitting.
RD	Green	Turns on when the module is receiving.

### **■ STATION ADDRESS**

Station Address is selected between 60H and 7FH in hexadecimal. (Because of simple I/O certain numbers may not be selectable depending on the master types. Refer to the instruction manual of the master unit.)

The left switch determines the MSD, while the right switch does the LSD of the address.

(Factory setting: 61H)



#### **■ OPERATING MODE**

#### • MECHATROLINK MODE

Choose MECHATROLINK-I or -II, and the data size. SW1-1 and SW1-2 are used.

SW1-1	SW1-2	MECHATROLINK
OFF	OFF	MECHATROLINK-II (32 byte mode) (*)
ON	OFF	MECHATROLINK-II (17 byte mode)
OFF	ON	Unused
ON	ON	MECHATROLINK-I (17 byte mode)
		•

(\*) Factory setting

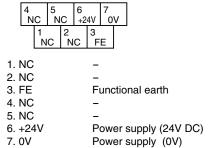
Caution! - SW1-3 and SW1-4 are unused. Be sure to turn off unused channels.

#### **■ DISCRETE OUTPUT STATUS INDICATOR LED**

LED green indicators shows the signal status.

ON: LED ON OFF: LED OFF

#### **■ POWER SUPPLY TERMINAL ASSIGNMENT**



### ■ OUTPUT TERMINAL ASSIGNMENT

	10 V		11 Y	1	12 Y	3	13 Y	'5	14 Y	7	15 Y	9	16 Y	11	17 Y	13	18 Y	
1 V	_	2 Y	0	3 Y	2	4 Y	<b>'</b> 4	5 Y	6	6 Y	8	7 Y	10	8 Y	12	9 Y	14	

	28 V	+	29 Y		30 Y		31 Y2	21	32 Y:		33 Y2		34 Y2		35 Y2		36 Y3	
19 V	_	20 Y	16	21 Y	18	22 Y:		23 Y2		24 Y2	24	25 Y2		26 Y2		27 Y:	30	

NO.	ID	FUNCTION	NO.	ID	FUNCTION
1	V–	Out. Common	10	V+	External excitation
2	Y0	Output 0	11	Y1	Output 1
3	Y2	Output 2	12	Y3	Output 3
4	Y4	Output 4	13	Y5	Output 5
5	Y6	Output 6	14	Y7	Output 7
6	Y8	Output 8	15	Y9	Output 9
7	Y10	Output 10	16	Y11	Output 11
8	Y12	Output 12	17	Y13	Output 13
9	Y14	Output 14	18	Y15	Output 15

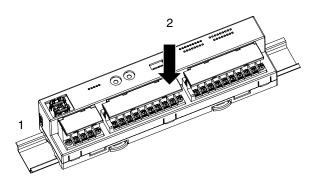
NO.	ID	FUNCTION	NO.	ID	FUNCTION
19	V–	Out. Common	28	V+	External excitation
20	Y16	Output 16	29	Y17	Output 17
21	Y18	Output 18	30	Y19	Output 19
22	Y20	Output 20	31	Y21	Output 21
23	Y22	Output 22	32	Y23	Output 23
24	Y24	Output 24	33	Y25	Output 25
25	Y26	Output 26	34	Y27	Output 27
26	Y28	Output 28	35	Y29	Output 29
27	Y30	Output 30	36	Y31	Output 31

# **MOUNTING INSTRUCTIONS**

# **■ DIN RAIL MOUNTING**

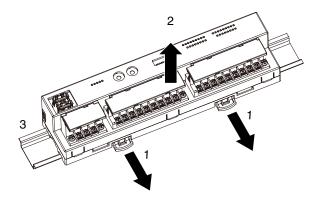
#### Mounting

- 1) Set the upper hook at the rear side of the unit on the DIN rail.
- 2) Push in the lower.



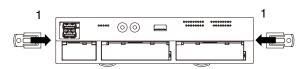
# Dismounting

- 1) Push down the DIN rail mounter slider with tip of a minus screwdriver.
- 2) Pull the lower of the unit.
- 3) Remove the upper hook of the unit from the DIN rail.

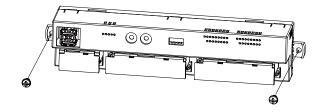


# **■ SURFACE MOUNTING**

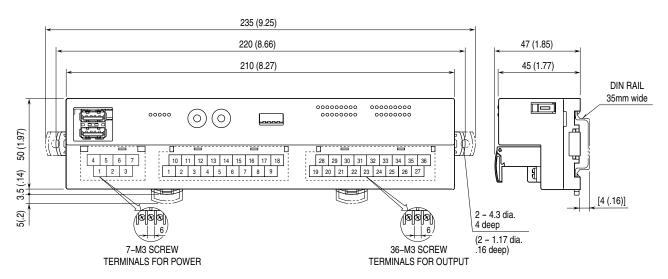
1) Insert the two DIN rail mounter sliders until it clicks once, as shown below.



2) Mount the unit with M4 screws referring the Mounting Requirements. (Torque: 1.4N·m)

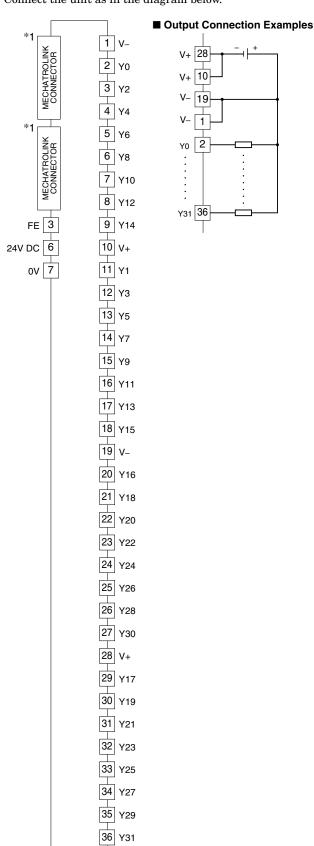


# **EXTERNAL DIMENSIONS** unit: mm (inch)



# **CONNECTION DIAGRAM**

Connect the unit as in the diagram below.



#### \*1. MECHARTROLINK connectors are internally connected. The network cable can be connected to either one.

Note: In order to improve EMC performance, bond the FE terminal to ground.

Caution: FE terminal is NOT a protective conductior terminal.

# **MOUNTING REQUIREMENTS** unit: mm (inch)



# WIRING INSTRUCTIONS

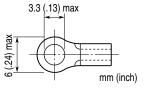
#### **■** TORQUE

Wiring screw for separable terminal: 0.5 N m Fixing screw for separable terminal: 0.5 N m

# ■ SOLDERLESS TERMINAL mm (inch)

Refer to the drawing below for recommended ring tongue terminal size. Spade tongue type is also applicable. Solderless terminals with insulation sleeve do not fit.

- Recommended manufacturer: Japan Solderless Terminal MFG.Co.Ltd, Nichifu Co.,ltd
- Applicable wire size: 0.25 1.65 mm<sup>2</sup> (AWG 22 16)



# ■ HOW TO UNMOUNT THE SEPARABLE TERMINAL

The separable terminal of the unit is 2 piece constructions. It is possible to remove the terminal by loosening two screws of terminal alternately.

# **MECHATROLINK COMMUNICATION**

# ■ MECHATROLINK-I

Baud rate: 4 Mbps

Transmission distance: 50 m max. Distance between stations: 30 cm min.

Transmission media: MECHATROLINK cable (Model JEPMC-W6003-x-E, Yaskawa Controls Co., Ltd.)

Max. number of slaves: 15

(The maximum number of slaves might change depending on the master unit. Refer to the manual of the master unit.)

Transmission cycle: 2 msec. (fixed)

Data length: 17 byte

### **■ MECHATROLINK-II**

Baud rate: 10 Mbps

Transmission distance: 50 m max. Distance between stations: 50 cm min.

Transmission media: MECHATROLINK cable (Model JEPMC-W6003-x-E, Yaskawa Controls Co., Ltd.)

Max. number of slaves: 30

(The maximum number of slaves might change depending on the master unit. Refer to the manual of the master unit.)

Transmission cycle: 0.25msec., 0.5 msec., 1 msec., 1.5 msec., 2 msec., 2.5 msec., 3 msec., 4 msec., 8 msec. Data length: 17 byte / 32 byte selectable (Must choose identical data size for all stations within the network)

# **MECHATROLINK RELATED COMMANDS**

R7K4FML (Simple I/O) communicates with I/O service with no processer, therfore it uses a connectionless communication protocol. There is no application layer either; the R7K4FML interchanges I/O data via data link layer.

### ■ MECHATROLINK DATA LINK LAYER COMMAND DESCRIPTIONS

The following tables explain the two Commands supported by the R7K4FML.

# • MDS Command (04H) Data Format

BYTE	COMMAND	RESPONSE	REMARKS
0	MDS (04H)	S(0) (90H)	Message Data Search (MDS) Command: Read the ID from slave station(s) S(0): Response to MDS
1	0	ID	
2	0	110	
3	0	0	All 0
4	0	0	
5	0	0	
6	0	0	
7	0	0	
8	0	0	
9	0	0	
10	0	0	
11	0	0	
12	0	0	
13	0	0	
14	0	0	
15	0	0	
16	0	0	
17	0	0	Byte 17 through 31 are always 0 in the 32-byte mode.
:	:	:	These bytes are unavailable for MECHATROLINK-I and MECHATROLINK
31	0	0	II in the 17-byte mode.

# • CDRW Command (03H) Data Format

BYTE	COMMAND	RESPONSE	REMARKS
0	CDRW (03H)	ACK (01H)	Cyclic Data Read/Write (CDRW) Command: Link transmission Acknowledge (ACK): Positive response to CDRW
1	Out Data: Lowest	In Data: Lowest	Order of data: Little Endian
2			
3			
4			
5			
6			
7			
8			
9			
10			
11			
12			
13			
14			
15			
16	Out Data: Highest	In Data: Highest	
17			Byte17through 31 are unavailable for MECHATROLINK-I and
:			MECHATROLINK-II in the 17-byte mode.
31	(Out Data: Highest)	(In Data: Highest)	(Only available for MECHATROLINK-II in the 32-byte mode)

# I/O DATA DESCRIPTIONS

# ■ 17-BYTE MODE

• 32 points output data (Out Data)

Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	0
2	0	0	0	0	0	0	0	0
3	0	0	0	0	0	0	0	0
4	0	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0	0
:	0	0	0	0	0	0	0	0
12	0	0	0	0	0	0	0	0
13	Out 7	Out 6	Out 5	Out 4	Out 3	Out 2	Out 1	Out 0
14	Out 15	Out 14	Out 13	Out 12	Out 11	Out 10	Out 9	Out 8
15	Out 23	Out 22	Out 21	Out 20	Out 19	Out 18	Out 17	Out 16
16	Out 31	Out 30	Out 29	Out 28	Out 27	Out 26	Out 25	Out 24

# ■ 32-BYTE MODE

• 32 points output data (Out Data)

1 1 7													
Byte	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0					
0	0	0	0	0	0	0	0	0					
1	0	0	0	0	0	0	0	0					
2	0	0	0	0	0	0	0	0					
3	0	0	0	0	0	0	0	0					
4	0	0	0	0	0	0	0	0					
5	0	0	0	0	0	0	0	0					
:	0	0	0	0	0	0	0	0					
28	0	0	0	0	0	0	0	0					
29	Out 7	Out 6	Out 5	Out 4	Out 3	Out 2	Out 1	Out 0					
30	Out 15	Out 14	Out 13	Out 12	Out 11	Out 10	Out 9	Out 8					
31	Out 23	Out 22	Out 21	Out 20	Out 19	Out 18	Out 17	Out 16					
32	Out 31	Out 30	Out 29	Out 28	Out 27	Out 26	Out 25	Out 24					

0: OFF 1: ON

At the loss of communication, output is hold. (last data correctly received is hold)