

## Plug-in Signal Conditioners M-UNIT

### SELF-SYNCH TRANSMITTER

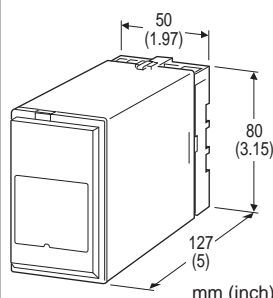
(field-programmable)

#### Functions & Features

- Converting position signal from a self-synchronizing motor into a DC signal proportional to the rotating shaft position
- Micro-processor based
- Linearization
- Loop testing via hand-held programmer PU-2x
- Offset adjustable via front multi-turn screwdriver adjustment
- High-density mounting

#### Typical Applications

- Position indicator using self-synch
- Tank gauge
- Sounding level meter



## MODEL: JS-1[1]-[2]

### ORDERING INFORMATION

- Code number: JS-1[1]-[2]  
Specify a code from below for each [1] and [2].  
(e.g. JS-1A-B)
- Input range (e.g. 270°)
- Special output range (For codes Z & 0)
- Use Ordering Information Sheet (No. ESU-1669) to specify linearization data when the I/O signals are nonlinear.

### INPUT

1: Self-synch signal

### [1] OUTPUT

#### Current

- A: 4 – 20 mA DC (Load resistance 750  $\Omega$  max.)
- B: 2 – 10 mA DC (Load resistance 1500  $\Omega$  max.)
- C: 1 – 5 mA DC (Load resistance 3000  $\Omega$  max.)
- D: 0 – 20 mA DC (Load resistance 750  $\Omega$  max.)
- E: 0 – 16 mA DC (Load resistance 900  $\Omega$  max.)

F: 0 – 10 mA DC (Load resistance 1500  $\Omega$  max.)

G: 0 – 1 mA DC (Load resistance 15 k $\Omega$  max.)

Z: Specify current (See OUTPUT SPECIFICATIONS)

#### Voltage

1: 0 – 10 mV DC (Load resistance 10 k $\Omega$  min.)

2: 0 – 100 mV DC (Load resistance 100 k $\Omega$  min.)

3: 0 – 1 V DC (Load resistance 1000  $\Omega$  min.)

4: 0 – 10 V DC (Load resistance 10 k $\Omega$  min.)

5: 0 – 5 V DC (Load resistance 5000  $\Omega$  min.)

6: 1 – 5 V DC (Load resistance 5000  $\Omega$  min.)

4W: -10 – +10 V DC (Load resistance 10 k $\Omega$  min.)

5W: -5 – +5 V DC (Load resistance 5000  $\Omega$  min.)

0: Specify voltage (See OUTPUT SPECIFICATIONS)

### [2] POWER INPUT

#### AC Power

B: 100 V AC

C: 110 V AC

D: 115 V AC

F: 120 V AC

G: 200 V AC

H: 220 V AC

J: 240 V AC

### RELATED PRODUCTS

- JX configurator connection kit (model: JXCON)
- Programming Unit (model: PU-2x)

### GENERAL SPECIFICATIONS

**Construction:** Plug-in

**Connection:** M3.5 screw terminals

**Housing material:** Flame-resistant resin (black)

**Isolation:** Input to output to power

**Offset adjustments:** 0 to 360° (front)

**Zero adjustment:** -5 to +5 % (front)

**Span adjustment:** 95 to 105 % (front)

**Linearization:** 16 points max. within the range of -15.00 – +115.00 % input or output; represented as percentage of full-scale

**Adjustments:** Programming Unit (model: PU-2x); input range, offset, linearization data, zero and span, input angle & coordinates, etc.

### INPUT SPECIFICATIONS

**Input:** Self-synch signal

**Measurement range:** 0 – 360°

**Input range:** 60 – 360° (270° for default)

**Input resistance:** 1 M $\Omega$  min.

**Rated input voltage:** 90 V AC

## OUTPUT SPECIFICATIONS

- **DC Current:** 0 – 20 mA DC
- Minimum span:** 1 mA
- Offset:** Max. 1.5 times span
- Load resistance:** Output drive 15 V max.
- **DC Voltage:** -10 – +20 V DC
- Span:** Min. 5 mV, max. 20 V
- Offset:** Max. 1.5 times span
- Load resistance:** Output drive 1 mA max.; at  $\geq 0.5$  V

## INSTALLATION

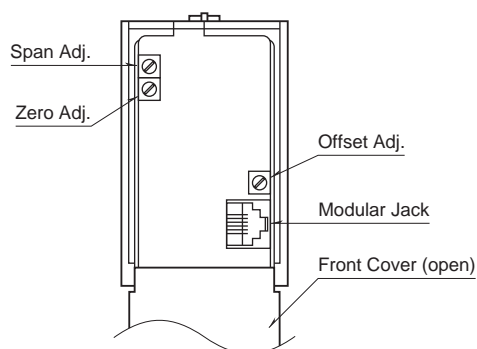
### Power input

- **AC:** Operational voltage range: rating  $\pm 10$  %, 50/60  $\pm 2$  Hz, approx. 3 VA
- Operating temperature:** -5 to +55°C (23 to 131°F)
- Operating humidity:** 30 to 90 %RH (non-condensing)
- Mounting:** Surface or DIN rail
- Weight:** 350 g (0.77 lbs)

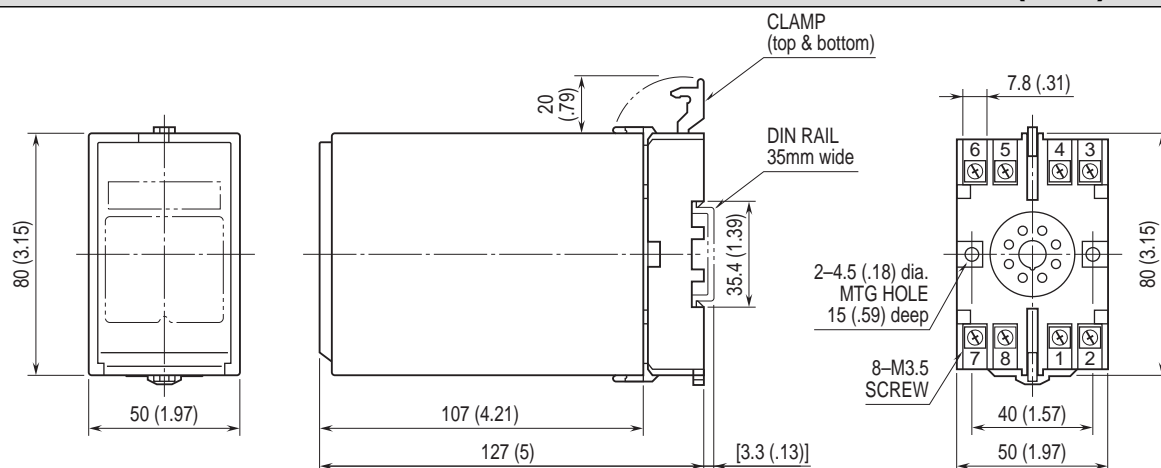
## PERFORMANCE in percentage of span

- Accuracy:**  $\pm 0.2$  % or  $\pm 0.5^\circ$ , whichever is greater (gain  $\leq 1$ )  
accuracy =  $[\pm 0.2 \text{ } \%( \pm 0.5^\circ ) \times \text{gain}]$  with the gain  $\geq 1$
- Temp. coefficient:**  $\pm 0.015$  %/°C ( $\pm 0.008$  %/°F)
- Response time:** Approx. 2 sec. (0 – 90 %)
- Line voltage effect:**  $\pm 0.1$  % over voltage range
- Insulation resistance:**  $\geq 100$  M $\Omega$  with 500 V DC
- Dielectric strength:** 2000 V AC @1 minute (input to output to power to ground)

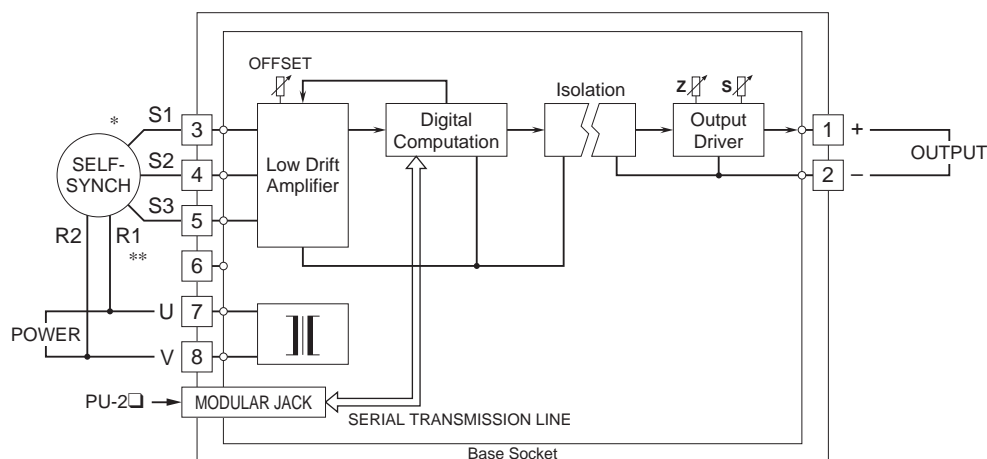
## EXTERNAL VIEW



## EXTERNAL DIMENSIONS & TERMINAL ASSIGNMENTS unit: mm (inch)



## SCHEMATIC CIRCUITRY & CONNECTION DIAGRAM



- \* The output increases when the self-synch rotates clockwise. For changing the operation to counterclockwise, replace the connection of the S2 and S3.
- \*\* Be sure that the polarity of the power input to the JS matches to the self-synch input polarity. When the connection is reversed, the JS output will be shifted by 180°.



Specifications are subject to change without notice.